

Through the Looking Glass ... and what Alice found there

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Frank Mittelbach
frank.mittelbach@latex-project.org

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John Tenniel, 1870

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1 From the looking glass story

Time and space



Time and space

Placing figures on pages (general formula)

$$\binom{\text{pages} + \text{figures} - 1}{\text{figures}} = ?$$

Placing figures on pages (one per page maximum)

$$\binom{\text{pages}}{\text{figures}} = ?$$

Examples (assuming 1 second per quality assessment)

- 16 pages, 9 figures → 11440 trials → 3.1 hours
- 90 pages, 28 figures → 1.548×10^{23} trials → 4.91×10^{15} years

So what now?



Can it be helped a little?

Takayama 2009

2 The dynamic programming methodology

Defining the problem

Input model

- A sequence of text blocks $T = \{t_1, t_2, \dots, t_n\}$
- A sequence of (figure) floats $F = \{f_1, f_2, \dots, f_\ell\}$
- (possibly some more float sequences — ignored for now)

Layout model

- A sequence of spreads S_1, S_2, \dots, S_k
 - with columns/pages (sizes may differ)
 - with areas for floats
 - constraints for the filling process
 - some further auxiliary information
-

Defining the problem (continued)

Paginations

- A mapping $p : T \cup F \rightarrow \{1, 2, \dots, k\}$ such that

$$\begin{aligned} p(t_i) \leq p(t_j) & \quad \text{for } 1 \leq i < j \leq n \\ p(f_i) \leq p(f_j) & \quad \text{for } 1 \leq i < j \leq \ell \end{aligned}$$

- \mathcal{P} is the set of all possible paginations of $T \cup F$

Objective function (cost function)

- A function $Q : \mathcal{P} \rightarrow \mathfrak{R}$

Optimization task

- We seek: $p_0 \in \mathcal{P}$ such that $Q(p_0) \leq Q(p)$ for all $p \in \mathcal{P}$
-

What can we do?

(Getting requirements for Q)

Example 1: Make a gut decision

- I.e., look at each pagination (for a second) and decide
- Clearly not workable:
 - **Already for “Through the Looking Glass” that takes longer than the current age of the universe**

Example 2: Base decision on call-out/float distance

- I.e., how many pages do I need to turn to reach a float
 - Linear formula: solvable using dynamic programming
 - **Quadratic formula: NP-complete as shown by Plass**

Example 3: Recto/verso criteria

- E.g., penalize if call-out and float are on the same type of page
 - **Again NP-complete as shown by Plass**
-

The dynamic programming methodology

When possible?

Problem consists of overlapping subproblems

- Clearly, that's the case (with sensible subproblems)
- We denote with $\mathcal{P}_{(S_i, \dots, S_j)_{c,d}}^{a,b}$ to mean
 - all paginations of text blocks t_a, \dots, t_b and figures f_c, \dots, f_d onto spreads S_i, \dots, S_j

- Examples:

$$\begin{aligned} \mathcal{P}_{(S_1, S_2)_{1,2}}^{1,80} \times \mathcal{P}_{(S_3, S_4)_{3,4}}^{81,150} &\subset \mathcal{P}_{(S_1, \dots, S_4)_{1,4}}^{1,150} \\ \mathcal{P}_{(S_1, \dots, S_3)_{1,2}}^{1,110} \times \mathcal{P}_{(S_4)_{3,4}}^{111,150} &\subset \mathcal{P}_{(S_1, \dots, S_4)_{1,4}}^{1,150} \\ \mathcal{P}_{(S_1, S_2)_{1,2}}^{1,80} \times \mathcal{P}_{(S_3)_{\emptyset, \emptyset}}^{81,110} &\subset \mathcal{P}_{(S_1, \dots, S_3)_{1,2}}^{1,110} \end{aligned}$$

Problem exhibits optimal substructure (optimality principle)

- The tricky bit
- A problem exhibits optimal substructure if
 - the optimal solution to the problem incorporates only optimal solutions to its subproblems;
 - the subproblems can be solved independently.
- Now what does this mean?

The dynamic programming methodology

Optimality principle

What does it mean?

- Assume we search for p_0 with $Q(p_0)$ minimal and

$$p_0 \in \mathcal{P}_{(S_1, \dots, S_4)_{1,4}}^{1,150}$$

- Assume further that we find

$$p_0 \in \mathcal{P}_{(S_1)_{1,1}}^{1,35} \times \mathcal{P}_{(S_2)_{2,2}}^{36,80} \times \mathcal{P}_{(S_3)_{\emptyset, \emptyset}}^{81,110} \times \mathcal{P}_{(S_4)_{3,4}}^{111,150}$$

... then the optimality principle means that

- p_0 (suitably restricted) is also an optimal solution for

$$\mathcal{P}_{(S_1)_{1,1}}^{1,35} \quad \mathcal{P}_{(S_1, S_2)_{1,2}}^{1,80} \quad \mathcal{P}_{(S_1, \dots, S_3)_{1,2}}^{1,110}$$

- and many others, e.g., $\mathcal{P}_{(S_2, \dots, S_4)_{2,4}}^{36,150}$ etc.

The dynamic programming methodology

Applying it

If dynamic programming is applicable we can

- solve each subproblem only once
- and remember the result
- construct the optimal solution of a bigger subproblem by extending and combining smaller subproblems

Example:

- Find the best way to put t_1, \dots, t_b and f_1, \dots, f_d onto spreads S_1, \dots, S_i :

$$\mathcal{P}_{(S_1, \dots, S_i)_{1,d}}^{1,b}$$

$$\mathcal{P}_{(S_1, \dots, S_i)_{1,d}}^{1,b} \supset \mathcal{P}_{(S_1, \dots, S_{i-1})_{1,c}}^{1,a} \times \mathcal{P}_{(S_i)_{c+1,d}}^{a+1,b}$$

$$\mathcal{P}_{(S_1, \dots, S_i)_{1,d}}^{1,b} \supset \mathcal{P}_{(S_1, \dots, S_{i-1})_{1,c'}}^{1,a'} \times \mathcal{P}_{(S_i)_{c'+1,d}}^{a'+1,b}$$

⋮

The dynamic programming methodology

Applying it

Example continued:

- In other words, we have

$$\mathcal{P}_{(S_1, \dots, S_i)_{1,d}}^{1,b} = \bigcup_{\substack{1 \leq a \leq b \\ 1 \leq c \leq d}} \mathcal{P}_{(S_1, \dots, S_{i-1})_{1,c}}^{1,a} \times \mathcal{P}_{(S_i)_{c+1,d}}^{a+1,b}$$

- So if we know the best way for each

$$\mathcal{P}_{(S_1, \dots, S_{i-1})_{1,c}}^{1,a}$$

then all we need to do is to calculate all the

$$\mathcal{P}_{(S_i)_{c+1,d}}^{a+1,b}$$

and apply Q to determine the best solution.

The dynamic programming methodology

Why does it sometimes fail?

Example continued:

- Suppose we have a pagination $p = p' \times p''$ with

$$p \in \mathcal{P}_{(S_1, \dots, S_i)_{1,d}}^{1,b}$$

and $p' \in \mathcal{P}_{(S_1, \dots, S_{i-1})_{1,c}}^{1,a} \quad p'' \in \mathcal{P}_{(S_i)_{c+1,d}}^{a+1,b}$

- Then we need to be able to calculate $Q(p)$ from $Q(p')$ and $Q(p'')$
- For example: $Q(p) = Q(p') + Q(p'') + \tilde{Q}(\mathcal{P}_{(S_1, \dots, S_{i-1})_{1,c}}^{1,a})$

But for the NP-complete cases this is

- not possible as the “quality” depends on where the call-out is (within p') in relation to the float (in p'')
- not depending on a fixed value based on $\mathcal{P}_{(S_1, \dots, S_{i-1})_{1,c}}^{1,a}$

3 The algorithms

The basic algorithm

(no floats)

Start up

- Let $A = \{a_0, a_1, a_2, \dots\}$ be elements from the text stream that have been identified as places where we can end a spread (plus info how we got there)
- Initially this contains just a_0 (start of document)

Main loop through all elements $t^* \in T$

- Check if we can successfully build a spread from one or more $a \in A$ to the current t^*
- For each new spread that ends, check which path gives the best result (according to Q) and add that one as a new element to A
 - (here we need the optimality principle)
- Whenever some $a_i \in A$ is too far away from t^* (overfull spread) remove it from A

The basic algorithm continued

(no floats)

Finishing off

- Eventually, we will reach the end of the document ...
- ... then work from the best solution backwards through all the elements we passed through
- **That defines our optimal solution**

Complexity

- The outer loop has n elements
- The inner loop is the size of A which is
 - bounded by a constant if all spreads have the same structure $\rightarrow O(c \cdot n) = O(n)$
 - otherwise it can be at most $n \rightarrow O(n^2)$

The extended algorithm

(with floats)

When starting up

- Compile info about each call-out

When t^* is identified as a new endpoint for a spread

- Prepare a list of all possible float placements for the next spread (conservative)
- Add a new $a \in A$ for each of them

When finishing off

- We need to deal with the case of unplaced floats
 - We can, for example, add them on further spreads (with some extra costs)
 - or drop them as “non-solutions”

The extended algorithm continued

(with floats)

Complexity

- The outer loop has n elements
- The inner loop is the size of A :
 - The number of elements ending in a different t^* is either
 - * $O(n)$ for fixed spread structure
 - * or $O(n^2)$ otherwise
 - For each new t^* we compile the set of all potentially possible float placements for the next spread
 - * This number is bounded by a constant (available space!)
 - * Any of the available floats might be the first
- Thus
 - If the spread all have the same structure $\rightarrow O(n \cdot \ell)$
 - otherwise $\rightarrow O(n^2 \cdot \ell)$
- Floats add a complexity factor in the size of their stream!

Float rules (structuring the approach)

Different types of rules

Rule types

- Absolute rule: placement not allowed if violated
- Preference rule: placement is (un)favorable

Call-out / float relations

- Floats are placed in order of their first/main call-out
 - Different streams are (usually) independent
- A float must appear after its call-out ...
 - same or later column (**usual approach**)
 - strictly after (**fairly restrictive**)
 - same page or spread or later (**difficult with greedy algorithms; involves reformatting**)
 - must be placed in their subsection (**dangerous**)
 - must be visible from the call-out (**very dangerous**)

Float rules (structuring the approach)

Different types of rules, continued

Rules for placement

- There cannot be more than x floats on a single page
- The top area of a column may receive a maximum of y floats, the bottom area of z floats
- If more than $x\%$ of the space on a column is occupied by floats then no normal text will appear in that column
- Every column must contain a minimum of $x\%$ of text
- All the floats are stacked vertically vertically at the top of a page; alternative: they can appear at the top or bottom (but not in both places)
- Floats can be horizontally placed if they are visually compatible (e.g., have identical heights); might also be requested for floats placed in adjacent columns

Float rules (structuring the approach)

Different types of rules, continued

Rules for the inner structure of a float

- Position of caption/legend based on float size
- Position of caption/legend based on placement
- Float size alterations (cropping of graphics, etc.)

Pruning (dropping supposedly bad solutions)

- Too many unplaced floats **and** x previous columns have no floats allocated
 - But documents may have many call-outs close by (**danger to drop too much**) But only if the floats could have placed there (**difficult to check**)
- Distance between call-out and float too large
 - Described this way creates dependencies between subproblems, thus violate the optimality principle (**difficult to implement correctly**)
- Other ideas ...
 - **Topic for further research!**

Applying float rules ...

Evaluate when deciding next float placement

- Pruning:
 - drop as soon as possible
- Absolute rules (for a spread):
 - drop if violated
- Preference rules (for a spread):
 - add cost charge

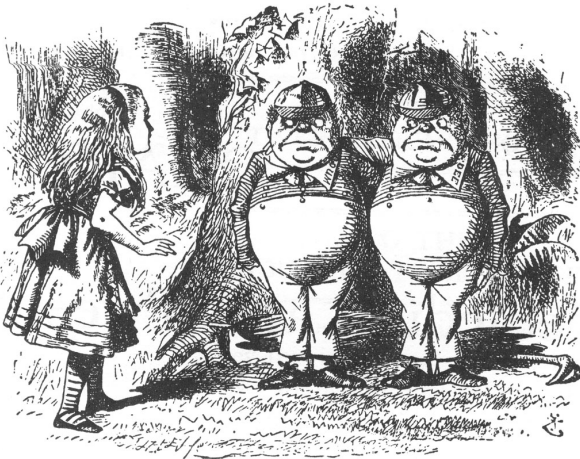
Evaluate when adding a call-out to a trial placement

- Call-out constraint rules (absolute):
 - remove $a \in A$ if violated
- Call-out constraint rules (preference):
 - add cost charge to $a \in A$

4 Aesthetics only

Designs without call-out constraints

(A bit of a horror scenario)



John Tenniel, 1870

Designs without call-out constraints

(A bit of a horror scenario)

What does this mean?

- No rules that favor a certain region (such as low distance from the call-out)
- The objective function only implements local aesthetics
- Thus the placement of floats mainly affects the quality through a better or worse fit of the text blocks

Consequences

- Dynamic programming would still work, as we can interpret this as the case in which
 - all call-outs are at the beginning of the document
 - the objective function adds a zero cost for the distance from the call-out
- But that means that pruning not really possible (**what would be the criteria?**)

Designs without call-out constraints

Managing the complexity

Just do it externally

- Advantage: fast
- Disadvantage: no interaction with formatting the text

Guiding the placement

- Advantage: interaction with text placement (while still fairly fast)
- Disadvantage: difficult to control
- **More research necessary!**

Mischief managed!



Hope I was able to reveal something new for you.
Thanks all around!

John Tenniel, 1870
